

70(b): Transformation from Spherical Polar to Eulerian Angles.

Consider the angular velocity in the spherical polar and Eulerian coordinate systems:

$$\begin{aligned}\underline{\omega} &= \omega_r \underline{e}_r + \omega_\theta \underline{e}_\theta + \omega_\phi \underline{e}_\phi \\ &= \omega_1 \underline{e}_1 + \omega_2 \underline{e}_2 + \omega_3 \underline{e}_3\end{aligned} \quad (1)$$

It follows that:

$$\omega_r^2 + \omega_\theta^2 + \omega_\phi^2 = \omega_1^2 + \omega_2^2 + \omega_3^2 \quad (2)$$

Denote the spherical polar angle by θ_1 and ϕ_1 and the Eulerian angle by θ , ϕ and ψ . So

$$\begin{aligned}\underline{\omega} &= \dot{\phi}_1 \cos \theta_1 \underline{e}_r - \dot{\phi}_1 \sin \theta_1 \underline{e}_\theta + \dot{\theta}_1 \underline{e}_\phi \\ &= (\dot{\phi} \sin \theta \sin \psi + \dot{\theta} \cos \psi) \underline{e}_1 + (\dot{\phi} \sin \theta \cos \psi - \dot{\theta} \sin \psi) \underline{e}_2 \\ &\quad + (\dot{\phi} \cos \theta + \dot{\psi}) \underline{e}_3\end{aligned} \quad (3)$$

It follows that:

$$\begin{aligned}\dot{\phi}_1^2 + \dot{\theta}_1^2 &= \dot{\phi}^2 \sin^2 \theta + \dot{\theta}^2 + (\dot{\phi} \cos \theta + \dot{\psi})^2 \\ &= \dot{\phi}^2 + \dot{\theta}^2 + 2\dot{\phi}\dot{\psi} \cos \theta + \dot{\psi}^2\end{aligned}$$

$$\boxed{\dot{\phi}_1^2 + \dot{\theta}_1^2 = \dot{\phi}^2 + \dot{\theta}^2 + \dot{\psi}(2\dot{\phi} \cos \theta + \dot{\psi})} \quad (4)$$

In the special case: $\phi_1 = \phi$, $\theta_1 = \theta$ - (5)

then:

$$\dot{\psi} = -2\dot{\phi} \cos \theta \quad \text{or} \quad \dot{\psi} = 0 \quad (6)$$